

Concurrent Abstract Predicates

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Outline

- Language and Operational Semantics
- Worlds (Logical Memory)
- Assertions
- Interferences
- Judgments
- Proof Rules and Soundness
- Examples
- Conclusions and Related Work

Language

(Cmd) $C ::= \mathbf{skip} \mid c \mid f \mid \langle C \rangle \mid C_1; C_2 \mid C_1 + C_2 \mid C^* \mid C_1 \parallel C_2 \mid$
 $\text{let } f_1 = C_1 \dots f_n = C_n \text{ in } C$

$\text{if}(B) C_1 \text{ else } C_2 \stackrel{\text{def}}{=} (\text{assume}(B); C_1) + (\text{assume}(\neg B); C_2)$

$\text{while}(B) C \stackrel{\text{def}}{=} (\text{assume}(B); C)^*; \text{assume}(\neg B)$

- $c \in \mathcal{P}(\text{Heap} \times \text{Heap})$: basic command
- How to model Stack ?
- Allow mutual recursion ?

Operational Semantics

$$\boxed{\eta \in \text{FEnv} \stackrel{\text{def}}{=} \text{FName} \rightarrow \text{Cmd}}$$

$$\frac{(C, h) \xrightarrow{\eta[f_1 \mapsto C_1 \dots f_n \mapsto C_n]} (C', h')}{(\text{let } f_1 = C_1 \dots f_n = C_n \text{ in } C, h) \xrightarrow{\eta} (\text{let } f_1 = C_1 \dots f_n = C_n \text{ in } C', h')}$$

$$\frac{}{(\text{let } \dots \text{ in } \mathbf{skip}, h) \xrightarrow{\eta} (\mathbf{skip}, h)} \quad \frac{f \in \text{dom}(\eta)}{(f, h) \xrightarrow{\eta} (\eta(f), h)} \quad \frac{(h, h') \in c \quad h' \neq \mathbf{fault}}{(c, h) \xrightarrow{\eta} (\mathbf{skip}, h')}$$

$$\frac{(C, h) \xrightarrow{\eta} (C_1, h')}{(C; C', h) \xrightarrow{\eta} (C_1; C', h')} \quad \frac{}{(\mathbf{skip}; C, h) \xrightarrow{\eta} (C, h)} \quad \frac{}{(C^*, h) \xrightarrow{\eta} (\mathbf{skip} + (C; C^*), h)}$$

$$\frac{}{(C_1 + C_2, h) \xrightarrow{\eta} (C_1, h)} \quad \frac{}{(C_1 + C_2, h) \xrightarrow{\eta} (C_2, h)} \quad \frac{(C, h) \xrightarrow{\eta^*} (\mathbf{skip}, h')}{(\langle C \rangle, h) \xrightarrow{\eta} (\mathbf{skip}, h')}$$

$$\frac{(C_1, h) \xrightarrow{\eta} (C'_1, h')}{(C_1 \parallel C_2, h) \xrightarrow{\eta} (C'_1 \parallel C_2, h')} \quad \frac{(C_2, h) \xrightarrow{\eta} (C'_2, h')}{(C_1 \parallel C_2, h) \xrightarrow{\eta} (C_1 \parallel C'_2, h')} \quad \frac{}{(\mathbf{skip} \parallel \mathbf{skip}, h) \xrightarrow{\eta} (\mathbf{skip}, h)}$$

Operational Semantics

$$\boxed{\eta \in \text{FEnv} \stackrel{\text{def}}{=} \text{FName} \rightarrow \text{Cmd}}$$

$$\begin{array}{ccc} \frac{(C_1, h) \xrightarrow{\eta} \text{fault}}{(C_1; C_2, h) \xrightarrow{\eta} \text{fault}} & \frac{(C_1, h) \xrightarrow{\eta} \text{fault}}{(C_1 \| C_2, h) \xrightarrow{\eta} \text{fault}} & \frac{(C_2, h) \xrightarrow{\eta} \text{fault}}{(C_1 \| C_2, h) \xrightarrow{\eta} \text{fault}} \\[2ex] \frac{f \notin \text{dom}(\eta)}{(f, h) \xrightarrow{\eta} \text{fault}} & \frac{(h, \mathbf{fault}) \in c}{(c, h) \xrightarrow{\eta} \text{fault}} & \frac{(C, h) \xrightarrow{\eta^*} \text{fault}}{(\langle C \rangle, h) \xrightarrow{\eta} \text{fault}} \end{array}$$

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Worlds (Logical Memory)

$$H_L, pr_L \quad \boxed{\begin{array}{c} r_1 \\ H_1, pr_1, l_1 \end{array}} \cdots \boxed{\begin{array}{c} r_n \\ H_n, pr_n, l_n \end{array}}$$

$$w \in \text{World} \stackrel{\text{def}}{=} \{(l, s) \in \text{LState} \times \text{SState} \mid \text{wf}(l, s)\}$$

$$l \in \text{LState} \stackrel{\text{def}}{=} \text{Heap} \times \text{Perm}$$

$$s \in \text{SState} \stackrel{\text{def}}{=} \text{RName} \xrightarrow{\text{fin}} (\text{LState} \times \text{IAssn})$$

Worlds (Logical Memory)

$$H_L, pr_L \quad \boxed{\begin{array}{c} r_1 \\ H_1, pr_1, I_1 \end{array}} \cdots \boxed{\begin{array}{c} r_n \\ H_n, pr_n, I_n \end{array}}$$

$$pr \in \text{Perm} \stackrel{\text{def}}{=} \text{Token} \rightarrow [0, 1]$$

$$t, (r, \gamma, \vec{v}) \in \text{Token} \stackrel{\text{def}}{=} \text{RName} \times \text{AName} \times \text{Val}^*$$

$$I ::= \gamma(\vec{x}) : \exists \vec{y}. (P \rightsquigarrow Q) \mid I_1, I_2$$

Worlds (Logical Memory)

$$H_L, pr_L \quad \boxed{\begin{array}{c} r_1 \\ H_1, pr_1, I_1 \end{array}} \cdots \boxed{\begin{array}{c} r_n \\ H_n, pr_n, I_n \end{array}}$$

$$w \oplus w' \stackrel{\text{def}}{=} \begin{cases} (w_L \oplus w'_L, w_S) & \text{if } w_S = w'_S \\ \perp & \text{otherwise.} \end{cases}$$

$$H_L \oplus H'_L = H_L \uplus H'_L$$

$$pr_L \oplus pr'_L = \lambda t. pr_L(t) +_{\leq 1} pr'_L(t)$$

Worlds (Logical Memory)

$$H_L, pr_L \quad \boxed{\begin{array}{c} r_1 \\ H_1, pr_1, I_1 \end{array}} \cdots \boxed{\begin{array}{c} r_n \\ H_n, pr_n, I_n \end{array}}$$

$$\text{wf}(l, s) \stackrel{\text{def}}{\iff} \lfloor (l, s) \rfloor \text{ is defined } \wedge \\ \forall r, \gamma, \vec{v}. \lfloor (l, s) \rfloor_P(r, \gamma, \vec{v}) > 0 \implies (\gamma, \vec{v}) \in \text{adom}((s(r))_2)$$

$$\lfloor (l, s) \rfloor \stackrel{\text{def}}{=} l \oplus \left(\bigoplus_{r \in \text{dom}(s)} (s(r)) \right)_1$$

$$\begin{aligned} \text{adom}(\gamma(x_1, \dots, x_n) : \exists \vec{y}. (P \rightsquigarrow Q)) &\stackrel{\text{def}}{=} \{(\gamma, (v_1, \dots, v_n)) \mid v_i \in \mathbf{Val}\} \\ \text{adom}(I_1, I_2) &\stackrel{\text{def}}{=} \text{adom}(I_1) \cup \text{adom}(I_2) \end{aligned}$$

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Assertions

(Assn) $P, Q ::= \text{emp} \mid E_1 \mapsto E_2 \mid P * Q \mid P -\circledast Q \mid \text{false} \mid P \Rightarrow Q \mid \exists x. P \mid \circledast x. P \mid$
 $\text{all}(I, r) \mid [\gamma(E_1, \dots, E_n)]_\pi^r \mid \boxed{P}_I^r \mid \alpha(E_1, \dots, E_n)$

(BAssn) $p, q ::= \text{emp} \mid E_1 \mapsto E_2 \mid p * q \mid p -\circledast q \mid \text{false} \mid p \Rightarrow q \mid \exists x. p \mid \circledast x. p$

- x, y, \dots : Free logical variables
- α, β, \dots : Abstract predicates

Assertion Semantics

$$\begin{aligned}
 \llbracket E_1 \mapsto E_2 \rrbracket_{\delta,i} &\stackrel{\text{def}}{=} \left\{ (l, s) \mid \begin{array}{l} \text{dom}(l_H) = \{\llbracket E_1 \rrbracket_i\} \wedge l_H(\llbracket E_1 \rrbracket_i) = \llbracket E_2 \rrbracket_i \\ \wedge l_P = \mathbf{0}_{\text{Perm}} \wedge s \in \text{SState} \end{array} \right\} \\
 \llbracket \text{emp} \rrbracket_{\delta,i} &\stackrel{\text{def}}{=} \{((\emptyset, \mathbf{0}_{\text{Perm}}), s) \mid s \in \text{SState}\} \\
 \llbracket P_1 * P_2 \rrbracket_{\delta,i} &\stackrel{\text{def}}{=} \{w_1 \oplus w_2 \mid w_1 \in \llbracket P_1 \rrbracket_{\delta,i} \wedge w_2 \in \llbracket P_2 \rrbracket_{\delta,i}\} \\
 \llbracket P_1 -\circledast P_2 \rrbracket_{\delta,i} &\stackrel{\text{def}}{=} \{w \mid \exists w_1, w_2. w_2 = w \oplus w_1 \wedge w_1 \in \llbracket P_1 \rrbracket_{\delta,i} \wedge w_2 \in \llbracket P_2 \rrbracket_{\delta,i}\} \\
 \llbracket \circledast x. P \rrbracket_{\delta,i} &\stackrel{\text{def}}{=} \bigcup_W \left\{ \bigoplus_v W(v) \mid \forall v. W(v) \in \llbracket P \rrbracket_{\delta,i[x \mapsto v]} \right\}
 \end{aligned}$$

$$\delta \in \text{PEnv} \stackrel{\text{def}}{=} \text{PName} \times \text{Val}^* \rightarrow \mathcal{P}(\text{World})$$

$$i \in \text{Interp} \stackrel{\text{def}}{=} \text{Var} \rightarrow \text{Val}$$

Assertion Semantics

$$\llbracket \text{all}(I, r) \rrbracket \stackrel{\text{def}}{=} \left\{ (\emptyset, \bigoplus_{(\gamma, \vec{v}) \in \text{adom}(I)} [(r, \gamma, \vec{v}) \mapsto 1]) \right\}$$

$$\llbracket [\gamma(E_1, \dots, E_n)]_{\pi}^r \rrbracket_{\delta, i} \stackrel{\text{def}}{=} \left\{ ((\emptyset, [(\llbracket r \rrbracket_i, \gamma, \llbracket E_1 \rrbracket_i, \dots, \llbracket E_n \rrbracket_i) \mapsto \llbracket \pi \rrbracket_i]), s) \mid \begin{array}{l} s \in \text{SState} \wedge \\ \llbracket \pi \rrbracket_i \in (0, 1] \end{array} \right\}$$

$$\llbracket \boxed{P}_I^r \rrbracket_{\delta, i} \stackrel{\text{def}}{=} \{ ((\emptyset, \mathbf{0}_{\text{Perm}}), s) \mid \exists l. (l, s) \in \llbracket P \rrbracket_{\delta, i} \wedge s(\llbracket r \rrbracket_i) = (l, \llbracket I \rrbracket_i) \}$$

$$\llbracket \alpha(E_1, \dots, E_n) \rrbracket_{\delta, i} \stackrel{\text{def}}{=} \delta(\alpha, \llbracket E_1 \rrbracket_i, \dots, \llbracket E_n \rrbracket_i)$$

$$\llbracket P \rrbracket_{\delta, i} \stackrel{\text{def}}{=} \{ (l, s) \in \llbracket P \rrbracket_{\delta, i} \mid \text{wf}((l, s)) \}$$

$$\delta \in \text{PEnv} \stackrel{\text{def}}{=} \text{PName} \times \text{Val}^* \rightarrow \mathcal{P}(\text{World})$$

$$i \in \text{Interp} \stackrel{\text{def}}{=} \text{Var} \rightarrow \text{Val}$$

Simple Equalities

$$\boxed{P}_I^r * \boxed{Q}_I^r \iff \boxed{P \wedge Q}_I^r$$

$$\boxed{\boxed{P}_I^r * Q}_{I'}^{r'} \iff \boxed{P}_I^r * \boxed{Q}_{I'}^{r'}$$

Nesting is necessary

$$\text{Locked}(x) \equiv \exists r. [\text{UNLOCK}]_1^r * \boxed{x \mapsto 1}_{I(r,x)}^r$$

$$\boxed{\text{Locked}(x)}_K^s \iff \boxed{\exists r. [\text{UNLOCK}]_1^r * \boxed{x \mapsto 1}_{I(r,x)}^r}_K^s$$

$$\iff \boxed{\exists r. [\text{UNLOCK}]_1^r}_K^s * \boxed{x \mapsto 1}_{I(r,x)}^r$$

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Interference Semantics

$$I ::= \gamma(\vec{x}) : \exists \vec{y}. (P \rightsquigarrow Q) \mid I_1, I_2$$

$$\llbracket I_1, I_2 \rrbracket_\delta(r, \gamma, \vec{v}) \stackrel{\text{def}}{=} \llbracket I_1 \rrbracket_\delta(r, \gamma, \vec{v}) \cup \llbracket I_2 \rrbracket_\delta(r, \gamma, \vec{v})$$

$$\llbracket \gamma(\vec{x}) : \exists \vec{y}. (P \rightsquigarrow Q) \rrbracket_\delta(r, \gamma', \vec{v}) \stackrel{\text{def}}{=} \left\{ (s, s') \left| \begin{array}{l} \gamma' = \gamma \wedge (\forall r' \neq r. s(r') = s'(r')) \\ \wedge \exists l, l', l_0, I. s(r) = (l \oplus l_0, I) \wedge \\ s'(r) = (l' \oplus l_0, I) \wedge \\ \exists \vec{v}'. (l, s) \in \llbracket P \rrbracket_{\delta, [\vec{x} \mapsto \vec{v}, \vec{y} \mapsto \vec{v}']} \wedge \\ (l', s') \in \llbracket Q \rrbracket_{\delta, [\vec{x} \mapsto \vec{v}, \vec{y} \mapsto \vec{v}']} \end{array} \right. \right\}$$

$$\delta \in \text{PEnv} \stackrel{\text{def}}{=} \text{PName} \times \text{Val}^* \rightarrow \mathcal{P}(\text{World})$$

$$(r, \gamma, \vec{v}) \in \text{Token} \stackrel{\text{def}}{=} \text{RName} \times \text{AName} \times \text{Val}^*$$

$$s \in \text{SState} \stackrel{\text{def}}{=} \text{RName} \xrightarrow{\text{fin}} (\text{LState} \times \text{IAssn})$$

Guarantee

$$G^c \stackrel{\text{def}}{=} \left\{ (w, w') \mid \begin{array}{l} \exists r, I, \ell_1, \ell_2. \ r \notin \text{dom}(w_S) \wedge w'_S = w_S[r \mapsto (\ell_1, I)] \wedge \\ w_L = \ell_1 \oplus \ell_2 \wedge w'_L = \ell_2 \oplus \langle \text{all}(I, r) \rangle \end{array} \right\}$$

$$G_\delta \stackrel{\text{def}}{=} \left\{ (w, w') \mid \begin{array}{l} ((\exists r, \gamma, \vec{v}. (w_S, w'_S) \in \llbracket (w_S(r))_2 \rrbracket_\delta(r, \gamma, \vec{v}) \wedge \\ (w_L)_P(r, \gamma, \vec{v}) > 0) \vee w_S = w'_S) \wedge \lfloor w \rfloor_P = \lfloor w' \rfloor_P \end{array} \right\} \cup G^c \cup (G^c)^{-1}$$

$$\overline{G}_\delta \stackrel{\text{def}}{=} G_\delta \cap \{(w, w') \mid \lfloor w \rfloor_H = \lfloor w' \rfloor_H\}$$

$$\widehat{G}_\delta \stackrel{\text{def}}{=} (\overline{G}_\delta)^*; G_\delta; (\overline{G}_\delta)^*$$

What goes wrong with this?

$$\widehat{G}_\delta = (G_\delta)^*$$

Rely

$$R^c \stackrel{\text{def}}{=} \left\{ (w, w') \mid \begin{array}{l} \exists r, \ell, I. r \notin \text{dom}(w_S) \wedge w'_L = w_L \wedge w'_S = w_S[r \mapsto (\ell, I)] \wedge \\ \lfloor w' \rfloor \text{ defined} \wedge (\forall \gamma, \vec{v}. \lfloor w' \rfloor_P(r, \gamma, \vec{v}) = 0) \end{array} \right\}$$

$$R_\delta \stackrel{\text{def}}{=} \left\{ (w, w') \mid \begin{array}{l} \exists r, \gamma, \vec{v}. (w_S, w'_S) \in \llbracket (w_S(r))_2 \rrbracket_\delta(r, \gamma, \vec{v}) \wedge \\ w_L = w'_L \wedge \lfloor w \rfloor_P(r, \gamma, \vec{v}) < 1 \end{array} \right\} \cup R^c \cup (R^c)^{-1}$$

Stability

Definition 4.2 (Stability). $\text{stable}_\delta(P)$ holds iff for all w, w' and i , if $w \in \llbracket P \rrbracket_{\delta,i}$ and $(w, w') \in R_\delta$, then $w' \in \llbracket P \rrbracket_{\delta,i}$.

Similarly, a predicate environment is stable if and only if all the predicates it defines are stable.

Definition 4.3 (Predicate Environment Stability). $\text{pstable}(\delta)$ holds iff for all $X \in \text{ran}(\delta)$, for all w and w' , if $w \in X$ and $(w, w') \in R_\delta$, then $w' \in X$.

Repartitioning

Definition 4.1 (Repartitioning). $P \Longrightarrow_{\delta}^{\{p\}\{q\}} Q$ holds if and only if, for every variable interpretation i and world w_1 in $\llbracket P \rrbracket_{\delta,i}$, there exists a heap h_1 in $\llbracket p \rrbracket_i$ and a residual heap h' such that

- $h_1 \oplus h' = \lfloor w_1 \rfloor_H$; and such that $h_2 \oplus h'$ defined ?
- for every heap h_2 in $\llbracket q \rrbracket_i$, there exists a world w_2 in $\llbracket Q \rrbracket_{\delta,i}$ such that
 - $h_2 \oplus h' = \lfloor w_2 \rfloor_H$; and
 - the update is allowed by the guarantee: that is, $(w_1, w_2) \in \hat{G}_{\delta}$.

We write $P \Longrightarrow_{\delta} Q$ as a shorthand for $P \Longrightarrow_{\delta}^{\{\text{emp}\}\{\text{emp}\}} Q$.

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Judgments

$$\Delta; \Gamma \vdash \{P\} C \{Q\}$$

$$\Delta; \Gamma \models \{P\} C \{Q\}$$

can't $\forall \vec{x}. \alpha(\vec{x}) \equiv P$ be a sugar for $\forall \vec{x}. \alpha(\vec{x}) \Rightarrow P, \forall \vec{x}. P \Rightarrow \alpha(\vec{x})$?

Why do we need this?

$$\Delta ::= \emptyset \mid \Delta, \forall \vec{x}. P \Rightarrow Q \mid \overbrace{\Delta, \forall \vec{x}. \alpha(\vec{x}) \equiv P}^{\text{Why do we need this?}} \text{ s.t. } \alpha \notin \Delta$$

$$\Gamma ::= \emptyset \mid \Gamma, \{P\} f \{Q\} \text{ s.t. } f \notin \Gamma$$

Configuration Safety

Definition 4.4 (Configuration safety). C, w, η, δ, i, Q safe_0 always holds; and $C, w, \eta, \delta, i, \text{safe}_{n+1}$ iff the following four conditions hold:

1. $\forall w'$, if $(w, w') \in (R_\delta)^*$ then $C, w', \eta, \delta, i, Q$ safe_n ;
2. $\neg((C, \lfloor w \rfloor_H) \xrightarrow{\eta} \text{fault})$;
3. $\forall C', h'$, if $(C, \lfloor w \rfloor_H) \xrightarrow{\eta} (C', h')$, then there $\exists w'$ such that $(w, w') \in \widehat{G}_\delta$, $h' = \lfloor w' \rfloor_H$ and $C', w', \eta, \delta, i, Q$ safe_n ; and
4. if $C = \mathbf{skip}$, then $\exists w'$ such that $\lfloor w \rfloor_H = \lfloor w' \rfloor_H$, $(w, w') \in \widehat{G}_\delta$, and $w' \in \llbracket Q \rrbracket_{\delta, i}$.

$$\delta \in \text{PEnv} \stackrel{\text{def}}{=} \text{PName} \times \text{Val}^* \rightarrow \mathcal{P}(\text{World})$$

$$i \in \text{Interp} \stackrel{\text{def}}{=} \text{Var} \rightarrow \text{Val}$$

$$\eta \in \text{FEnv} \stackrel{\text{def}}{=} \text{FName} \rightarrow \text{Cmd}$$

Judgment Semantics

Definition 4.5 (Judgement Semantics). $\Delta; \Gamma \models \{P\} C \{Q\}$ holds iff

$$\forall i, n. \forall \delta \in \llbracket \Delta \rrbracket. \forall \eta \in \llbracket \Gamma \rrbracket_{n, \delta, i}. \forall w \in \llbracket P \rrbracket_{\delta, i}. C, w, \eta, \delta, i, Q \text{ safe}_{n+1}$$

Step-indexing:

- Easy for dealing with recursive functions.
- But, might be problematic with memoization.
- There might be a coinductive solution.

$$\llbracket \emptyset \rrbracket \stackrel{\text{def}}{=} \{\delta \mid \text{pstable}(\delta)\}$$

~~$$\llbracket \Delta, \forall \vec{x}. \alpha(\vec{x}) \equiv P \rrbracket \stackrel{\text{def}}{=} \llbracket \Delta \rrbracket \cap \{\delta \mid \text{pstable}(\delta) \wedge \forall \vec{v}. \delta(\alpha, \vec{v}) = \llbracket P \rrbracket_{\delta, [\vec{x} \mapsto \vec{v}]} \}$$~~

$$\llbracket \Delta, \forall \vec{x}. P \Rightarrow Q \rrbracket \stackrel{\text{def}}{=} \llbracket \Delta \rrbracket \cap \{\delta \mid \text{pstable}(\delta) \wedge \forall \vec{v}. \llbracket P \rrbracket_{\delta, [\vec{x} \mapsto \vec{v}]} \subseteq \llbracket Q \rrbracket_{\delta, [\vec{x} \mapsto \vec{v}]} \}$$

$$\llbracket \Gamma \rrbracket_{n, \delta, i} \stackrel{\text{def}}{=} \{\eta \mid \forall \{P\} f \{Q\} \in \Gamma. \forall w \in \llbracket P \rrbracket_{\delta, i}. \eta(f), w, \eta, \delta, i, Q \text{ safe}_n\}$$

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Proof Rules

$$\frac{}{\Delta; \Gamma \vdash \{P\} \text{skip} \{P\}} \text{ (SKIP)} \quad \frac{\Delta; \Gamma \vdash \{P\} C_1 \{P'\} \quad \Delta; \Gamma \vdash \{P\} C_2 \{P'\}}{\Delta; \Gamma \vdash \{P\} C_1 + C_2 \{P'\}} \text{ (CHOICE)}$$

$$\frac{\Delta; \Gamma \vdash \{P\} C_1 \{P''\} \quad \Delta; \Gamma \vdash \{P''\} C_2 \{P'\}}{\Delta; \Gamma \vdash \{P\} C_1; C_2 \{P'\}} \text{ (SEQ)} \quad \frac{\Delta; \Gamma \vdash \{P\} C \{P\}}{\Delta; \Gamma \vdash \{P\} C^* \{P\}} \text{ (LOOP)}$$

$$\frac{\Delta; \Gamma \vdash \{P_1\} C_1 \{Q_1\} \quad \Delta; \Gamma \vdash \{P_2\} C_2 \{Q_2\}}{\Delta; \Gamma \vdash \{P_1 * P_2\} C_1 \parallel C_2 \{Q_1 * Q_2\}} \text{ (PAR)} \quad \frac{\vdash_{\text{SL}} \{p\} C \{q\}}{\Delta; \Gamma \vdash \{p\} C \{q\}} \text{ (PRIM)}$$

$$\frac{\Delta; \Gamma \vdash \{P_1\} C \{Q\} \quad \Delta; \Gamma \vdash \{P_2\} C \{Q\}}{\Delta; \Gamma \vdash \{P_1 \vee P_2\} C \{Q\}} \text{ (DISJ)} \quad \frac{x \notin \text{fv}(\Delta, \Gamma, P, C, Q) \quad \Delta; \Gamma \vdash \{P\} C \{Q\}}{\Delta; \Gamma \vdash \{\exists x. P\} C \{Q\}} \text{ (EX)}$$

All rules assume that the pre- and post-conditions of their judgments are stable.

Proof Rules

$$\frac{\vdash_{\text{SL}} \{p\} C \{q\} \quad \Delta \vdash P \Longrightarrow^{\{p\}\{q\}} Q}{\Delta; \Gamma \vdash \{P\} \langle C \rangle \{Q\}} \text{ (ATOMIC)}$$

$$\frac{\{P\} f \{Q\} \in \Gamma}{\Delta; \Gamma \vdash \{P\} f \{Q\}} \text{ (CALL)}$$

$$\frac{\begin{array}{c} \Delta; \Gamma \vdash \{P\} C \{Q\} \\ \Delta \vdash \text{stable}(R) \end{array}}{\Delta; \Gamma \vdash \{P * R\} C \{Q * R\}} \text{ (FRAME)}$$

$$\frac{\begin{array}{c} \Delta; \Gamma \vdash \{P'\} C \{Q'\} \\ \Delta \vdash P \Longrightarrow P' \quad \Delta \vdash Q' \Longrightarrow Q \end{array}}{\Delta; \Gamma \vdash \{P\} C \{Q\}} \text{ (CONSEQ)}$$

α occurs positively in R

$$\Delta \vdash \text{stable}(R) \quad \alpha \notin \Delta, \Gamma, P, Q$$

$$\frac{\Delta \vdash \Delta' \quad \Delta'; \Gamma \vdash \{P\} C \{Q\}}{\Delta; \Gamma \vdash \{P\} C \{Q\}} \text{ (PRED-I)}$$

$$\frac{\Delta, (\forall \vec{x}. \alpha(\vec{x}) \equiv R); \Gamma \vdash \{P\} C \{Q\}}{\Delta; \Gamma \vdash \{P\} C \{Q\}} \text{ (PRED-E)}$$

$$\frac{\begin{array}{c} \Delta; \Gamma \vdash \{P_1\} C_1 \{Q_1\} \quad \dots \quad \Delta; \Gamma \vdash \{P_n\} C_n \{Q_n\} \\ \Delta; \{P_1\} f_1 \{Q_1\}, \dots, \{P_n\} f_n \{Q_n\}, \Gamma \vdash \{P\} C \{Q\} \end{array}}{\Delta; \Gamma \vdash \{P\} \text{let } f_1 = C_1 \dots f_n = C_n \text{ in } C \{Q\}} \text{ (LET)}$$

Recursive Let is derivable.
But we need a rule
for eliminating unused Γ .

$$\Delta \vdash P \Longrightarrow^{\{p\}\{q\}} Q \text{ means } \forall \delta \in \llbracket \Delta \rrbracket. P \Longrightarrow_{\delta}^{\{p\}\{q\}} Q$$

$$\Delta \vdash \text{stable}(P) \text{ means } \forall \delta \in \llbracket \Delta \rrbracket. \text{stable}_{\delta}(P)$$

$$\Delta \vdash \Delta' \text{ means } \llbracket \Delta \rrbracket \subseteq \llbracket \Delta' \rrbracket.$$

All rules assume that the pre- and post-conditions of their judgments are stable.

Frame Rule Bug ?

$$\frac{\Delta; \Gamma \vdash \{P\} C \{Q\} \quad \Delta \vdash \text{stable}(R)}{\Delta; \Gamma \vdash \{P * R\} C \{Q * R\}} \text{ (FRAME)}$$

region name conflict ?

$$\vdash \{x \mapsto 0\} \text{ skip } \left\{ \boxed{x \mapsto 0}^r_{\emptyset} \right\} \\ \vdash \text{stable} \left(\boxed{y \mapsto 1}^r_{\emptyset} \right)$$

$$\left\{ x \mapsto 0 * \boxed{y \mapsto 1}^r_{\emptyset} \right\} \text{ skip } \left\{ \boxed{x \mapsto 0}^r_{\emptyset} * \boxed{y \mapsto 1}^r_{\emptyset} \right\}$$

My Thought (Maybe Wrong):

- Clients do not know which region names will be used by modules.
- So, if clients use some shared regions, how do they know the region names are not used by other abstract modules?
- In particular, when you frame in abstract predicates using Frame Rule, there is no guarantee that there are no region name conflicts.

Derived Rule for Module

$$\begin{array}{c}
 \Delta \vdash \{P_1\}C_1\{Q_1\} \quad \dots \quad \frac{\Delta \vdash \Delta' \quad \Delta'; \{P_1\}f_1\{Q_1\}, \dots \vdash \{P\}C\{Q\}}{\Delta; \{P_1\}f_1\{Q_1\}, \dots \vdash \{P\}C\{Q\}} \text{PRED-I} \\
 \hline
 \frac{\Delta \vdash \{P\} \text{let } f_1 = C_1 \dots f_n = C_n \text{ in } C \{Q\}}{\Delta' \vdash \{P\} \text{let } f_1 = C_1 \dots f_n = C_n \text{ in } C \{Q\}} \text{LET} \\
 \hline
 \Delta' \vdash \{P\} \text{let } f_1 = C_1 \dots f_n = C_n \text{ in } C \{Q\} \quad \text{PRED-E}
 \end{array}$$

Soundness

Theorem 4.6 (Soundness). *If $\Delta; \Gamma \vdash \{P\} C \{Q\}$, then $\Delta; \Gamma \models \{P\} C \{Q\}$.*

Lemma 4.7 (Abstract state locality). *If $(C, \lfloor w_1 \oplus w_2 \rfloor_H) \xrightarrow{\eta} (C', h)$ and $C, w_1, \eta, \delta, i, Q$ safe_n, then $\exists w'_1, w'_2$ such that $(C, \lfloor w_1 \rfloor_H) \xrightarrow{\eta} (C', \lfloor w'_1 \rfloor_H)$, $h = \lfloor w'_1 \oplus w'_2 \rfloor_H$, $(w_1, w'_1) \in \hat{G}_\delta$, and $(w_2, w'_2) \in (R_\delta)^*$.*

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Lock Specification for Client

$\Gamma :$

$$\begin{array}{lll}
 \{\text{isLock}(x)\} & \text{lock}(x) & \{\text{isLock}(x) * \text{Locked}(x)\} \\
 \{\text{Locked}(x)\} & \text{unlock}(x) & \{\text{emp}\} \\
 \{\text{emp}\} & \text{makelock}(n) & \left\{ \begin{array}{l} \exists x. \text{ret} = x \wedge \text{isLock}(x) * \text{Locked}(x) \\ * (x + 1) \mapsto _ * \dots * (x + n) \mapsto _ \end{array} \right\}
 \end{array}$$

$\Delta :$

$$\begin{array}{ll}
 \text{isLock}(x) & \iff \text{isLock}(x) * \text{isLock}(x) \\
 \text{Locked}(x) * \text{Locked}(x) & \iff \text{false}
 \end{array}$$

Lock Specification for Module

Additional Axioms Δ' :

$$\text{isLock}(x) \equiv \exists r. \exists \pi. [\text{LOCK}]_{\pi}^r * \boxed{(x \mapsto 0 * [\text{UNLOCK}]_1^r) \vee x \mapsto 1}_{I(r,x)}^r$$

$$\text{Locked}(x) \equiv \exists r. [\text{UNLOCK}]_1^r * \boxed{x \mapsto 1}_{I(r,x)}^r$$

$$I(r, x) \stackrel{\text{def}}{=} \left(\begin{array}{l} \text{LOCK: } x \mapsto 0 * [\text{UNLOCK}]_1^r \rightsquigarrow x \mapsto 1, \\ \text{UNLOCK: } x \mapsto 1 \rightsquigarrow x \mapsto 0 * [\text{UNLOCK}]_1^r \end{array} \right)$$

Lock Verification

```

{isLock(x)}
lock(x) {
  {  $\exists r. \pi. [\text{LOCK}]_{\pi}^r * \boxed{(\mathbf{x} \mapsto 0 * [\text{UNLOCK}]_1^r) \vee \mathbf{x} \mapsto 1}_{I(r,\mathbf{x})}^r$  }
  local b;
  do
    {  $\exists r. \pi. [\text{LOCK}]_{\pi}^r * \boxed{(\mathbf{x} \mapsto 0 * [\text{UNLOCK}]_1^r) \vee \mathbf{x} \mapsto 1}_{I(r,\mathbf{x})}^r$  }
     $\langle \mathbf{b} := \neg \text{CAS}(\&\mathbf{x}, 0, 1) \rangle$ ;
    {  $\exists r. \pi. \left( \boxed{\mathbf{x} \mapsto 1}_{I(r,\mathbf{x})}^r * [\text{LOCK}]_{\pi}^r * [\text{UNLOCK}]_1^r * \mathbf{b} = \text{false} \right) \vee$ 
      {  $\left( \boxed{(\mathbf{x} \mapsto 0 * [\text{UNLOCK}]_1^r) \vee \mathbf{x} \mapsto 1}_{I(r,\mathbf{x})}^r * [\text{LOCK}]_{\pi}^r * \mathbf{b} = \text{true} \right)$  }
    while(b)
    {  $\exists r. \boxed{\mathbf{x} \mapsto 1}_{I(r,\mathbf{x})}^r * [\text{LOCK}]_{\pi}^r * [\text{UNLOCK}]_1^r * \mathbf{b} = \text{false}$  }
  }
  {isLock(x) * Locked(x)}

```

Lock Verification

```
{Locked(x)}  
unlock(x) {  
  { $\exists r. [\text{UNLOCK}]_1^r * \boxed{\mathbf{x} \mapsto 1}_{I(r,\mathbf{x})}^r$ }  
   $\langle [\mathbf{x}] := 0 \rangle$ ;  
  { $\exists r. \boxed{\mathbf{x} \mapsto 0 * [\text{UNLOCK}]_1^r}_{I(r,\mathbf{x})}^r$ }  
  // Stabilise the assertion.  
  { $\exists r. \boxed{(\mathbf{x} \mapsto 0 * [\text{UNLOCK}]_1^r) \vee \mathbf{x} \mapsto 1}_{I(r,\mathbf{x})}^r$ }  
}  
{emp}
```

Lock Verification

```
{emp}
makelock(n) {
  local x := alloc(n + 1);
  {x ↦ _ * (x + 1) ↦ _ * ... * (x + n) ↦ _}
  [x] := 1;
  {x ↦ 1 * (x + 1) ↦ _ * ... * (x + n) ↦ _}
  // Create shared lock region.
  { $\exists r. \boxed{x \mapsto 1}^r_{I(r,x)} * [\text{LOCK}]_1^r * [\text{UNLOCK}]_1^r * (x + 1) \mapsto _ * \dots * (x + n) \mapsto _$ }
  return x;
}
{ $\exists x. \text{ret} = x \wedge \text{isLock}(x) * \text{Locked}(x) * (x + 1) \mapsto _ * \dots * (x + n) \mapsto _$ }
```

Set Specification for Client

$\Gamma :$

$\{in(h, v)\}$	$contains(h, v)$	$\{in(h, v) * ret = true\}$
$\{out(h, v)\}$	$contains(h, v)$	$\{out(h, v) * ret = false\}$
$\{own(h, v)\}$	$add(h, v)$	$\{in(h, v)\}$
$\{own(h, v)\}$	$remove(h, v)$	$\{out(h, v)\}$

$\Delta :$

$$own(h, v) * own(h, v) \implies false$$

where $own(h, v) := in(h, v) \vee out(h, v)$

$\{emp\} \quad mkemp() \quad \{\odot_v. out(ret, v)\}$

is needed to be a concurrent set

External Modules for Set

Lock Module

$\{\text{isLock}(x)\} \quad \text{lock}(x) \quad \{\text{isLock}(x) * \text{Locked}(x)\}$

$\{\text{Locked}(x)\} \quad \text{unlock}(x) \quad \{\text{emp}\}$

$\{\text{emp}\} \quad \text{makelock}(n) \quad \left\{ \begin{array}{l} \exists x. \text{ret} = x \wedge \text{isLock}(x) * \text{Locked}(x) \\ * (x + 1) \mapsto _ * \dots * (x + n) \mapsto _ \end{array} \right\}$

$\text{isLock}(x) \iff \text{isLock}(x) * \text{isLock}(x)$

$\text{Locked}(x) * \text{Locked}(x) \iff \text{false}$

Sequential Set Module

$\{\text{Set}(h, vs)\} \quad \text{scontains}(h, v) \quad \{\text{Set}(h, vs) * \text{ret} = (v \in vs)\}$

$\{\text{Set}(h, vs)\} \quad \text{sadd}(h, v) \quad \{\text{Set}(h, \{v\} \cup vs)\}$

$\{\text{Set}(h, vs)\} \quad \text{sremove}(h, v) \quad \{\text{Set}(h, vs \setminus \{v\})\}$

$\{\text{emp}\} \quad \text{mkemp}() \quad \{\text{Set}(\text{ret}, \emptyset)\}$

Set Specification for Module

Additional Axioms Δ' :

$$\text{in}(h, v) \equiv \exists s. \text{isLock}(h.\text{lock}) * [\text{SCHANGE}(v)]_1^s * \boxed{P_{\in}(h, v, s)}_{C(s, h)}^s$$

$$\text{out}(h, v) \equiv \exists s. \text{isLock}(h.\text{lock}) * [\text{SCHANGE}(v)]_1^s * \boxed{P_{\notin}(h, v, s)}_{C(s, h)}^s$$

$$C(s, h) \stackrel{\text{def}}{=} \left(\begin{array}{l} \text{SCHANGE}(v): \left(\begin{array}{l} \exists vs, ws. \text{Set}(h.\text{set}, vs) \\ * [\text{SGAP}(ws)]_1^s \wedge \\ vs \setminus \{v\} = ws \setminus \{v\} \end{array} \right) \rightsquigarrow \text{Locked}(h.\text{lock}) , \\ \text{SGAP}(ws): \text{Locked}(h.\text{lock}) \rightsquigarrow \text{Set}(h.\text{set}, ws) * [\text{SGAP}(ws)]_1^s \end{array} \right)$$

$$\text{allgaps}(s) \equiv \bigotimes ws. [\text{SGAP}(ws)]_1^s$$

$$P_{\triangleleft}(h, v, s) \equiv \exists vs. v \triangleleft vs \wedge \left(\begin{array}{l} (\text{allgaps}(s) * \text{Set}(h.\text{set}, vs)) \\ \vee \text{Locked}(h.\text{lock}) * ([\text{SGAP}(vs)]_1^s - \bigotimes \text{allgaps}(s)) \end{array} \right)$$

where $\triangleleft = \in$ or $\triangleleft = \notin$

Set Verification

$\{\text{out}(\mathbf{h}, \mathbf{v})\}$

`add(h, v)`

$\left\{ \exists s. \text{isLock}(\mathbf{h}.\text{lock}) * [\text{SCHANGE}(\mathbf{v})]_1^s * \boxed{P_{\notin}(\mathbf{h}, \mathbf{v}, s)}_{C(s, \mathbf{h})}^s \right\}$

`lock(h.lock);`

$\left\{ \exists s. \text{isLock}(\mathbf{h}.\text{lock}) * \text{Locked}(\mathbf{h}.\text{lock}) * [\text{SCHANGE}(\mathbf{v})]_1^s * \boxed{P_{\notin}(\mathbf{h}, \mathbf{v}, s)}_{C(s, \mathbf{h})}^s \right\}$

// use SCHANGE to extract Set predicate and SGAP permission.

$\left\{ \begin{aligned} &\exists s, vs. \text{isLock}(\mathbf{h}.\text{lock}) * [\text{SGAP}(vs \cup \{\mathbf{v}\})]_1^s * [\text{SCHANGE}(\mathbf{v})]_1^s * \text{Set}(\mathbf{h}.\text{set}, vs) \\ &* \boxed{\text{Locked}(\mathbf{h}.\text{lock}) * ([\text{SGAP}(vs \cup \{\mathbf{v}\})]_1^s \multimap \text{allgaps}(s))}_{C(s, \mathbf{h})}^s \end{aligned} \right\}$

`sadd(h.set, v);`

$\left\{ \begin{aligned} &\exists s, vs. \text{isLock}(\mathbf{h}.\text{lock}) * [\text{SGAP}(vs \cup \{\mathbf{v}\})]_1^s * [\text{SCHANGE}(\mathbf{v})]_1^s * \text{Set}(\mathbf{h}.\text{set}, vs \cup \{\mathbf{v}\}) \\ &* \boxed{\text{Locked}(\mathbf{h}.\text{lock}) * ([\text{SGAP}(vs \cup \{\mathbf{v}\})]_1^s \multimap \text{allgaps}(s))}_{C(s, \mathbf{h})}^s \end{aligned} \right\}$

// use SGAP permission to put back Set and SGAP permission.

$\left\{ \exists s. \text{isLock}(\mathbf{h}.\text{lock}) * \text{Locked}(\mathbf{h}.\text{lock}) * [\text{SCHANGE}(\mathbf{v})]_1^s * \boxed{P_{\in}(\mathbf{h}, \mathbf{v}, s)}_{C(s, \mathbf{h})}^s \right\}$

`unlock(h.lock);`

$\left\{ \exists s. \text{isLock}(\mathbf{h}.\text{lock}) * [\text{SCHANGE}(\mathbf{v})]_1^s * \boxed{P_{\in}(\mathbf{h}, \mathbf{v}, s)}_{C(s, \mathbf{h})}^s \right\}$

}

$\{\text{in}(\mathbf{h}, \mathbf{v})\}$

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Conclusions and Related Work

- Abstract Predicate
- Deny-Guarantee
- Context Logic
- B. Jacobs and F. Piessens. Modular full functional specification and verification of lock-free data structures.
- Alternative Approach: Linearizability