# Concurrent Separation Logic

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 $\frac{\{P \land B\}S\{Q\}}{\{P\}\text{await } B \text{ then } S\{Q\}}$ 

 $\frac{\{P_1\}S_1\{Q_1\}\dots\{P_n\}S_n\{Q_n\} \text{ are interference-free}}{\{P_1 \wedge \dots \wedge P_n\}S_1 \parallel \dots \parallel S_n\{Q_1 \wedge \dots \wedge Q_n\}}$ 

Interference-freedom is hard to prove and not composable.

#### Even more previously, but on life Hoare (1972)

 $\frac{\{P_1\}S_1\{Q_1\}\dots\{P_n\}S_n\{Q_n\} \text{ are } disjoint}{\{P_1 \land \dots \land P_n\}S_1 \parallel \dots \parallel S_n\{Q_1 \land \dots \land Q_n\}}$ 

Where *disjointness* is "they work with different data spaces". For shared *resources*, the following construct is added:



Hoare, Towards a Theory of Parallel Programming

- These systems statically ensure *cautiousness*.
- Shared variables accessed only in critical regions.
- Most concurrent systems are *daring*.
- Semaphores example:

P(s) critical code V(s)

• Rely/Guarantee allows this kind of interactions.



### Previously on CPL (2) Separation Logic

Assertions P, Q extended with

- $x \mapsto v$
- $P_1 * P_2$
- In  $\{P\}S\{Q\}$ :

"S can only access locations in the domain of P"

• Frame rule:

 $\frac{\{P\}S\{Q\}}{\{P*R\}S\{Q*R\}}$ 

• Parallel rule:

$$\frac{\{P_1\}S_1\{Q_1\}\dots\{P_n\}S_n\{Q_n\}}{\{P_1*\dots*P_n\}S_1\parallel\dots\parallel S_n\{Q_1*\dots*Q_n\}} \text{ conditions}$$

• Resource invariants. From S. Owicki and D. Gries. Verifying properties of parallel programs: An axiomatic approach.

Through the talk Owicki/Gries (O/G) mean this work.

- In {*P*}*S*{*Q*}:
  - "S owns locations in the domain of P"
- *Ownership Hypothesis*: A code fragment can access only those portions of state that it owns.
- Separation Property: At any time, the state can be partitioned into that owned by each process and each grouping of mutual exclusion.
- The proof system will ensure this property.

Par rule:

$$\frac{\{P_1\}S_1\{Q_1\}\dots\{P_n\}S_n\{Q_n\}}{\{P_1*\dots*P_n\}S_1\parallel\dots\parallel S_n\{Q_1*\dots*Q_n\}}$$

where **modify** $(S_i) \cap \mathbf{FV}(P_j, S_j, Q_j) = \emptyset$  for  $i \neq j$ 

- It is restrictive.
- But has its uses.

 $\{array(a, i, j)\}$ procedure msort(a, i, j) m := (i + j)/2;if i < j then  $(msort(a, i, m) \parallel msort(a, m + 1, j));$  merge(a, i, m + 1, j);  $\{sorted(a, i, j)\}$ 

We can split the array:

 $\begin{array}{l} \{array(a, i, m) * array(a, m + 1, j)\} \\ \{array(a, i, m)\} & \{array(a, m + 1, j)\} \\ (msort(a, i, m) & \parallel msort(a, m + 1, j)); \\ \{sorted(a, i, m)\} & \{sorted(a, m + 1, j)\} \\ & merge(a, i, m + 1, j) \\ & \{sorted(a, i, j)\} \end{array}$ 

Language with CCRs (O/G)

init; resource  $r_1$ (variable list)... $r_m$ (variable list)  $C_1 \parallel ... \parallel C_n$ 

We said x belongs to r if it's in r's list.

$$C ::= \mathbf{skip} \mid x := E \mid x := [E] \mid [E] := E' \mid C_1; C_2$$
$$\mid i := \mathbf{cons}(E_0, \dots, E_n) \mid \mathbf{dispose} E$$
$$\mid \mathbf{if} \ B \ \mathbf{then} \ C_1 \ \mathbf{else} \ C_2 \mid \mathbf{while} \ B \ \mathbf{do} \ C$$
$$\mid \mathbf{with} \ r \ \mathbf{when} \ B \ \mathbf{do} \ C$$

Brookes uses a less restricted syntax.

Restriction taken from Owicki/Gries to avoid interference:

- **1** a variable belongs *at most* to one resource;
- if x belongs to r, it can only appear within a parallel process inside a critical region for r;
- if x is changed in one process, it cannot appear in another unless it belongs to a resource.

In the presence of pointers these rules are not enough! Consider

 $[x] := 3 \parallel [y] := 4$ 

Separation conjunction will help us here.

### Proof rules

- Par rule not requiring looking at other's code.
- Each resource  $r_i$  has a *resource invariant*  $l_i$  satisfying:
  - any command x := ... where x ∈ FV(l<sub>i</sub>) must occur within a critical region for r<sub>i</sub>.
     In O/G they ask x to belong to r<sub>i</sub>.
  - Each  $I_i$  should be "precise" (to be defined).
- Rule for a program:

$$[P] init\{ \boxed{I_1 * \ldots * I_m} * P'\} \{P'\} C_1 \parallel \ldots \parallel C_n \{Q\}$$

$$\{P\}$$
init;
resource  $r_1$ (variable list)  $\ldots r_m$ (variable list)
$$C_1 \parallel \ldots \parallel C_n$$

$$\{\boxed{I_1 * \ldots * I_m} * Q\}$$

• Rule for critical region:

$$\frac{\{(P * I_i) \land B\}C\{Q * I_i\}}{\{P\}\text{with } r_i \text{ when } B \text{ do } C\{Q\}}$$

No other process modifies variables free in P or Q.

Brookes's rules:

$$\frac{[\Gamma, r_i(X) : I_i \vdash \{P\}C\{Q\}]}{\{P * I_i\} \text{resource } r_i \text{ in } C\{Q * I_i\}}$$

if  $r \notin \text{dom}(\Gamma)$ ,  $X \cap \text{owned}(\Gamma) = \emptyset$ ,  $\text{free}(I_i) \cap \text{owned}(\Gamma) = \emptyset$ , and  $I_i$  is precise. Where does X comes from?

• Rule for erasing temporal variables.

- Key point: there is "no interference from the outside".
- Process communication at explicit synchronization points.
- Dijkstra: "apart from the (rare) moments of explicit intercommunication, the individual processes are to be regarded as completely independent from each other".
- Ownership Hypothesis is essential.
- Well specified processes mind their own business.



$$P(s) = \text{with } s \text{ when } s > 0 \text{ do } s := s - 1$$
$$V(s) = \text{with } s \text{ when true do } s := s + 1$$
$$l_s = (s = 0 \land \text{emp}) \lor (s = 1 \land 10 \mapsto -)$$

$$\frac{\{(A * I_{s}) \land s > 0\}s := s - 1\{A' * I_{s}\}}{\{A\}\mathsf{P}(s)\{A'\}}$$
$$\frac{\{A * I_{s}\}s := s + 1\{A' * I_{s}\}}{\{A\}\mathsf{V}(s)\{A'\}}$$



$$\frac{\{(A * I_s) \land s > 0\}s := s - 1\{A' * I_s\}}{\{A\}\mathsf{P}(s)\{A'\}}$$

$$\{ (\overbrace{emp}^{A} * (\overbrace{free = 0 \land emp}) \lor (free = 1 \land 10 \mapsto -))) \land free > 0 \}$$

$$\{ free = 1 \land 10 \mapsto - \}$$

$$\{ free = 0 \land 10 \mapsto - \}$$

$$\{ (free = 0 \land emp) * 10 \mapsto - \}$$

$$\{ ((free = 0 \land emp) \lor (free = 1 \land 10 \mapsto -)) * \underbrace{10 \mapsto -}$$

$$\{ ((free = 0 \land emp) \lor (free = 1 \land 10 \mapsto -)) * \underbrace{10 \mapsto -} \}$$

$$\{10 \mapsto -\}$$

$$\{10 \mapsto -* \operatorname{emp}\}$$

$$free := 1; \ busy := 0;$$

$$\{(free = 1 \land 10 \mapsto -) * (busy = 0 \land \operatorname{emp})\}$$

$$\{((free = 1 \land 10 \mapsto -) \lor (free = 0 \land \operatorname{emp})) *$$

$$* ((busy = 1 \land 10 \mapsto -) \lor (busy = 0 \land \operatorname{emp}))\}$$

$$\{I_{free} * I_{busy}\}$$

What if we set both to 1?

## Ownership transfer

$$prog = \dots; \begin{pmatrix} x := cons(a, b); & \| & get(y); \\ put(x) & & use(y); \\ & & dispose(y); \end{pmatrix}$$

Where

 $put(x) \triangleq$  with buf when  $\neg full$  do c := x; full := true  $get(y) \triangleq$  with buf when full do y := c; full := false

- Prove that, either x is used and deallocated by the receiver,
- or it is not used (nor deallocated) by the receiver.
- As it should, it cannot prove x can be deallocated by the two processes.

# Logical garbage

- We'd like to prove: {emp}prog{emp}
- But we end up proving:  $\{emp\}prog\{I_{buf}\}$
- Where  $I_{buf} = (full \land c \mapsto -, -) \lor (\neg full \land emp)$
- But we know  $\neg full$ , but we cannot leak it (soundness of with).
- Remember:

$$\frac{\{(P * I_i) \land B\}C\{Q * I_i\}}{\{P\} \text{with } r_i \text{ when } B \text{ do } C\{Q\}}$$

No other process modifies variables free in P or Q.

- (We use the magic address 10 before because of this.)
- Who can save us now?

# Super-semaphore!



# Super-semaphore! Idea

• Add logical variables start and finish.

 $I_{buf} = \begin{array}{l} (\neg full \land start \land \neg finish \land emp) \\ \lor (full \land \neg start \land \neg finish \land c \mapsto -, -) \\ \lor (\neg full \land \neg start \land finish \land emp) \end{array}$ 

- start modified by **put**, finish modified by **get**.
- We can leak them out!

 $\{emp\}prog'\{I_{buf} * (emp \land \neg start \land finish)\}$ 

• Therefore getting

 $\{emp\}prog'\{emp\}$ 

• And then we erase them!

 $\{emp\}\mathit{prog}\{emp\}$ 

### Memory allocation

*list*  $x \triangleq (x = \mathsf{nil} \land \mathsf{emp}) \lor (\exists y. x \mapsto -, y * \mathit{list} y)$  $I_m = \mathit{list} f$ 

alloc $(x, a, b) \triangleq$  with *m* when true do if f = nil then x := cons(a, b)else x := f; f := x.2; x.1 := a; x.2 := b

dealloc(y)  $\triangleq$  with *m* when true do y.2 := *f*; *f* := y

Proved under invariant *list f*:

 $\{emp\}alloc(x, a, b)\{x \mapsto a, b\}$  $\{y \mapsto -, -\}dealloc(y)\{emp\}$ 

 We can replace cons and dispose by alloc and dealloc in our prog example:

$$prog = \dots; \begin{pmatrix} alloc(x, a, b); & || & get(y); \\ put(x) & use(y); \\ & dealloc(y); \end{pmatrix}$$

• Initialization requires the setup of *both* invariants:

full := false;resource buf(c, full), m(f)

• Once proved both invariants *I*<sub>buf</sub> and *I*<sub>m</sub> are set, the rest of the proof is maintained.

- Brookes's is *really* composable... (unified language).
- Key idea in rule for CCR:

$$\frac{\{(P * I_i) \land B\}C\{Q * I_i\}}{\{P\}\text{with } r_i \text{ when } B \text{ do } C\{Q\}}$$

No invariant needed in the conclusion!

Chapter 10. Skipped for the sake of time.

Interesting remark: This logic does not allow for dynamic resource allocation.

Are there logics with this capability?

## Reynolds Counterexample

- At the beginning we said "invariants should be precise".
- If not, then the system is incompatible with the rule

 $\frac{\{P\}C\{Q\} \quad \{P'\}C\{Q'\}}{\{P \land P'\}C\{Q \land Q'\}}$ 

• Counterexample:

resource r() $l_r =$ true  $C \triangleq$  with r when true do skip

### Reynolds Counterexample

• We derive  $\{\operatorname{emp} \lor 10 \mapsto -\}C\{\operatorname{emp}\}$ :

$$\frac{\overline{\{\mathsf{true}\}\mathsf{skip}\{\mathsf{true}\}}^{Skip}}{\{(\mathsf{emp} \lor 10 \mapsto -) * \mathsf{true}\}\mathsf{skip}\{\mathsf{emp} * \mathsf{true}\}}^{Conseq}}_{CCR}$$

Then 
$$\{10 \mapsto -\}C\{10 \mapsto -\}:$$
  

$$\frac{\{\operatorname{emp} \lor 10 \mapsto -\}C\{\operatorname{emp}\}}{\{\operatorname{emp} \wr C\{\operatorname{emp}\}}Conseq}$$

$$\frac{\operatorname{emp} \ast 10 \mapsto -\}C\{\operatorname{emp} \ast 10 \mapsto -\}}{\{10 \mapsto -\}C\{10 \mapsto -\}}Conseq$$

• Then  $\{10 \mapsto -\}C\{emp\}$ :  $\frac{\{emp \lor 10 \mapsto -\}C\{emp\}}{\{10 \mapsto -\}C\{emp\}}Conseq$  Applying the conjunction rule:

$$\frac{\{10 \mapsto -\}C\{10 \mapsto -\} \quad \{10 \mapsto -\}C\{\text{emp}\}}{\{10 \mapsto -\land 10 \mapsto -\}C\{\underbrace{10 \mapsto -\land \text{emp}}_{\text{false}}\}}$$

Blame the invariant!

(Or the precondition, in O/G, but not valid in this setting).

An invariant I is **precise** if for all states (s, h) there's at most one subheap h' s.t.

$$h' \subseteq h$$
,  $(s,h) \Vdash I$ ,  $(s,h') \Vdash I$ 

true is not precise...

Precise predicates let us split the heap in an unique way.

This is precisely what is needed to prove soundness!

## Precise precise definition

From Viktor's: *P* is precise iff  $\forall h_1, h'_1, h_2, h'_2$ ,

 $\operatorname{def}(h_1 * h_2)$  and  $h_1 * h_2 = h_1' * h_2'$  and  $(s, h_1) \Vdash P$  and  $(s, h_1') \Vdash P$ 

then  $h_1 = h'_1$ .

Not so restrictive in practice:

 $P ::= \operatorname{emp} | x \mapsto E | (P * P') | (P \land Q) | (Q \land P) | (B \land P) \lor (B' \land P')$ 

Brookes say other definition is possible (with P and Q being *intuitionistic* for Region and Resource, and just the precise part of the heap is used in the hypotheses of these rules).

# $I \vdash \{P\}C\{Q\}$

- State from / can be changed by other threads.
- State *P* is owned by *C*.
- *I* is maintained before, during, and after *C*.
- Definition of *safe*: A program *C* is safe to run under invariant *I* and precondition *P*, and will produce *Q*.
- Simpler proof. Bakes the frame rule into the definition of *safe*.

- All proved in Isabelle.
- Do not require abort semantics to prove soundness (in contrast with Brookes).
- Same proof for soundness without the conjunction rule *or* with precise invariants.
- Sharing read permissions!

$$\{10 \mapsto -\}x := [10] \parallel y := [10]\{10 \mapsto -\}$$

- $10 \mapsto = 10 \mapsto^{0.5} *10 \mapsto^{0.5} -$ .
- Can only update if  $10 \mapsto^1 -$ .
- Soundness of RGSep also proved (stay tuned!)

